

# Temporal Logic

## - Branching-time logic (1/2)

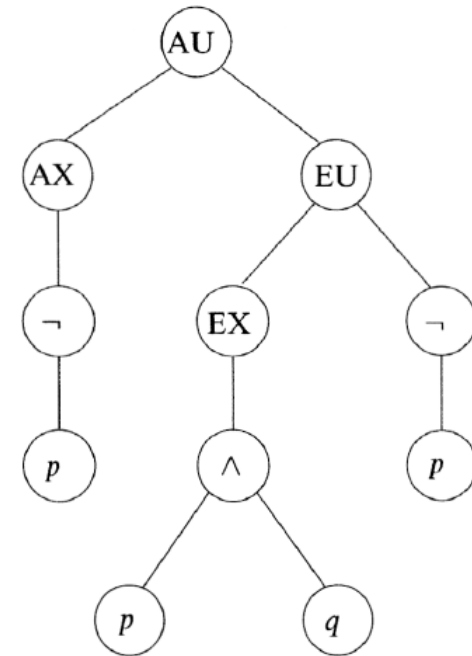
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# LTL vs. CTL

- LTL implicitly quantifies **universally** over paths
  - a state of a system satisfies an LTL formula if **all paths** from the given state satisfy it
  - properties which use **both** universal and existential path quantifiers cannot in general be model checked using LTL.
    - property  $\phi$  which use only universal path quantifiers can be checked using LTL by checking  $\neg\phi$
- Branching-time logic solve this limitation by quantifying paths explicitly
  - There **is** a reachable state satisfying  $q$ : **EF**  $q$ 
    - Note that we can check this property by checking LTL formula  $\phi = G \neg q$ 
      - If  $\phi$  is true, the property is false. If  $\phi$  is false, the property is true
  - From all reachable states satisfying  $p$ , it is **possible** to maintain  $p$  continuously until reaching a state satisfying  $q$ : **AG** ( $p \rightarrow E(p U q)$ )
  - Whenever a state satisfying  $p$  is reached, the system **can** exhibit  $q$  continuously forevermore: **AG** ( $p \rightarrow EG q$ )
  - There **is** a reachable state from which all reachable states satisfy  $p$ : **EF** **AG**  $p$

# Syntax of Computation Tree Logic (CTL)

- Def 3.12  $\phi = \perp \mid \top \mid p \mid \neg \phi \mid \phi \wedge \phi \mid \phi \vee \phi \mid \phi \rightarrow \phi \mid \text{AX } \phi$   
 $\mid \text{EX } \phi \mid \text{AF } \phi \mid \text{EF } \phi \mid \text{AG } \phi \mid \text{EG } \phi \mid \text{A } (\phi \text{ U } \phi) \mid \text{E } (\phi \text{ U } \phi)$ 
  - A: along all paths
  - E: along at least one path
- Precedence
  - AG, EG, AF, EF, AX, EX,  $\wedge$ ,  $\vee$ ,  $\rightarrow$ , AU, EU
- Note that the following formulas are **not** well-formed CTL formulas
  - EF G r
  - A  $\neg$ G  $\neg$  p
  - F (r U q)
  - EF (r U q)
  - AEF r
  - A ((r U q)  $\wedge$  (p U r))



$\text{A } [(\text{AX } \neg p) \text{ U } (\text{E } [(\text{EX } p \wedge q) \text{ U } \neg p])]$

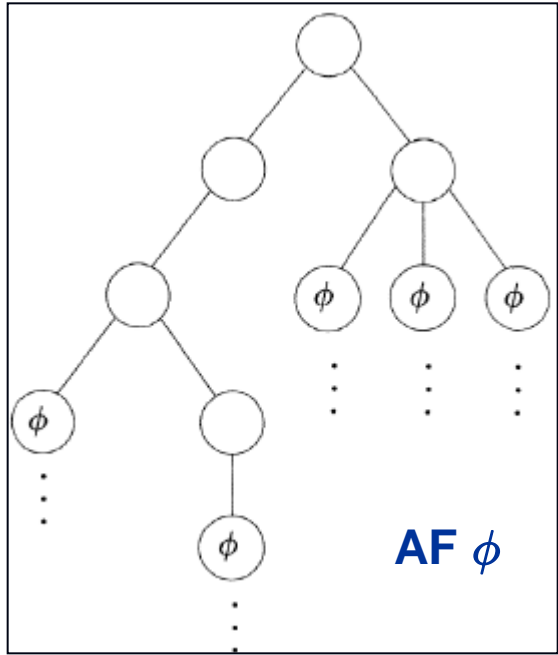
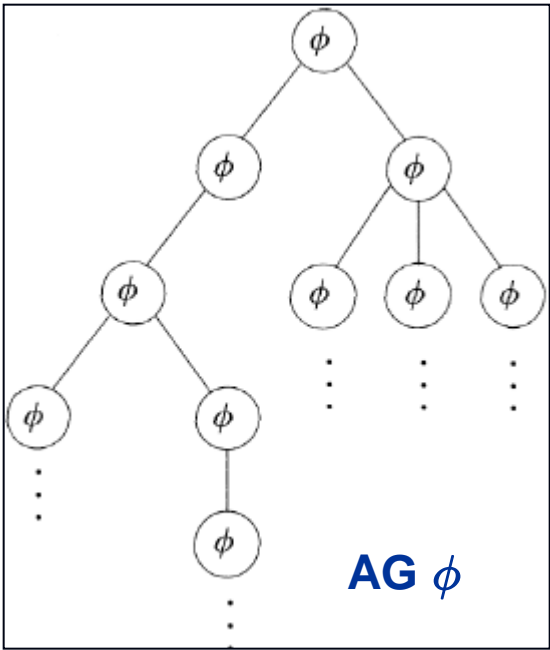
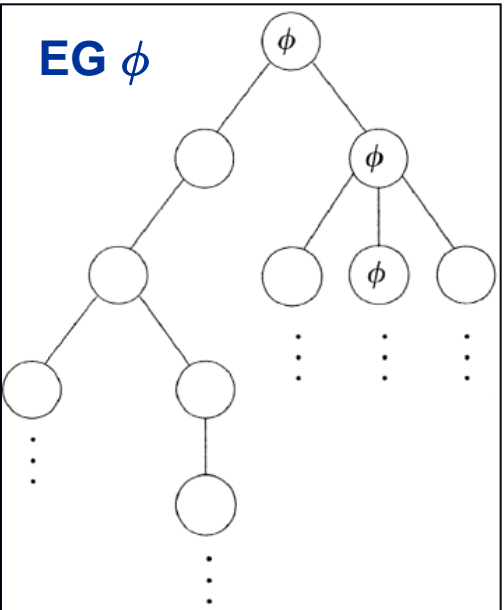
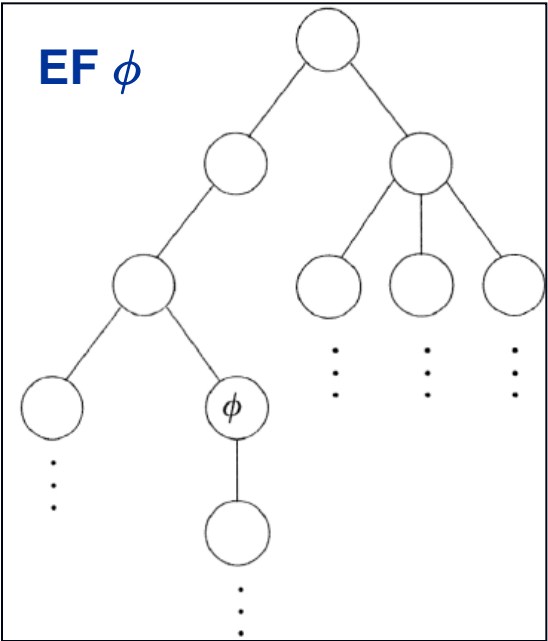
# Semantics of CTL (1/2)

- Def 3.15 Let  $\mathcal{M} = (S, \rightarrow, L)$  be a model for CTL,  $s$  in  $S$ ,  $\phi$  a CTL formula. The relation  $\mathcal{M}, s \models \phi$  is defined by structural induction on  $\phi$ . We omit  $\mathcal{M}$  if context is clear.
  - $\mathcal{M}, s \models \top$  and  $\mathcal{M}, s \not\models \perp$
  - $\mathcal{M}, s \models p$  iff  $p \in L(s)$
  - $\mathcal{M}, s \models \neg \phi$  iff  $\mathcal{M}, s \not\models \phi$
  - $\mathcal{M}, s \models \phi_1 \wedge \phi_2$  iff  $\mathcal{M}, s \models \phi_1$  and  $\mathcal{M}, s \models \phi_2$
  - $\mathcal{M}, s \models \phi_1 \vee \phi_2$  iff  $\mathcal{M}, s \models \phi_1$  or  $\mathcal{M}, s \models \phi_2$
  - $\mathcal{M}, s \models \phi_1 \rightarrow \phi_2$  iff  $\mathcal{M}, s \not\models \phi_1$  or  $\mathcal{M}, s \models \phi_2$
  - $\mathcal{M}, s \models \mathbf{AX} \phi$  iff for **all**  $s_1$  s.t.  $s \rightarrow s_1$  we have  $\mathcal{M}, s_1 \models \phi$ . Thus **AX** says “in **every next state**”
  - $\mathcal{M}, s \models \mathbf{EX} \phi$  iff for **some**  $s_1$  s.t.  $s \rightarrow s_1$  we have  $\mathcal{M}, s_1 \models \phi$ . Thus **EX** says “in **some next state**”

# Semantics of CTL (2/2)

- Def 3.15 Let  $\mathcal{M} = (S, \rightarrow, L)$  be a model for CTL,  $s$  in  $S$ ,  $\phi$  a CTL formula. The relation  $\mathcal{M}, s \models \phi$  is defined by structural induction on  $\phi$ . We omit  $\mathcal{M}$  if context is clear.
  - $\mathcal{M}, s \models \mathbf{AG} \phi$  iff for **all** paths  $s_1 \rightarrow s_2 \rightarrow s_3 \rightarrow \dots$  where  $s_1$  equals  $s$ , and **all**  $s_i$  along the path, we have  $\mathcal{M}, s_i \models \phi$ .
  - $\mathcal{M}, s \models \mathbf{EG} \phi$  iff there **is** a path  $s_1 \rightarrow s_2 \rightarrow s_3 \rightarrow \dots$  where  $s_1$  equals  $s$ , and **all**  $s_i$  along the path, we have  $\mathcal{M}, s_i \models \phi$ .
  - $\mathcal{M}, s \models \mathbf{AF} \phi$  iff for **all** paths  $s_1 \rightarrow s_2 \rightarrow s_3 \rightarrow \dots$  where  $s_1$  equals  $s$ , and there **is** some  $s_i$  s.t.  $\mathcal{M}, s_i \models \phi$ .
  - $\mathcal{M}, s \models \mathbf{EF} \phi$  iff there **is** a path  $s_1 \rightarrow s_2 \rightarrow s_3 \rightarrow \dots$  where  $s_1$  equals  $s$ , and there **is** some  $s_i$  s.t.  $\mathcal{M}, s_i \models \phi$ .
  - $\mathcal{M}, s \models \mathbf{A} [\phi_1 \mathbf{U} \phi_2]$  iff for **all** paths  $s_1 \rightarrow s_2 \rightarrow s_3 \rightarrow \dots$  where  $s_1$  equals  $s$ , that path satisfies  $\phi_1 \mathbf{U} \phi_2$
  - $\mathcal{M}, s \models \mathbf{E} [\phi_1 \mathbf{U} \phi_2]$  iff there **is** a path  $s_1 \rightarrow s_2 \rightarrow s_3 \rightarrow \dots$  where  $s_1$  equals  $s$ , that path satisfies  $\phi_1 \mathbf{U} \phi_2$

# Example (1/2)



# Example (2/2)

- $\mathcal{M}, s_0 \models p \wedge q$ ,  $\mathcal{M}, s_0 \models \neg r$ ,  $\mathcal{M}, s_0 \models T$
- $\mathcal{M}, s_0 \models EX (q \wedge r)$
- $\mathcal{M}, s_0 \models \neg AX (q \wedge r)$
- $\mathcal{M}, s_0 \models \neg EF (p \wedge r)$
- $\mathcal{M}, s_2 \models EG r$
- $\mathcal{M}, s_0 \models AF r$
- $\mathcal{M}, s_0 \models E [(p \wedge q) \cup r]$
- $\mathcal{M}, s_0 \models A [p \cup r]$
- $\mathcal{M}, s_0 \models AG (p \vee q \vee r \rightarrow EF EG r)$

