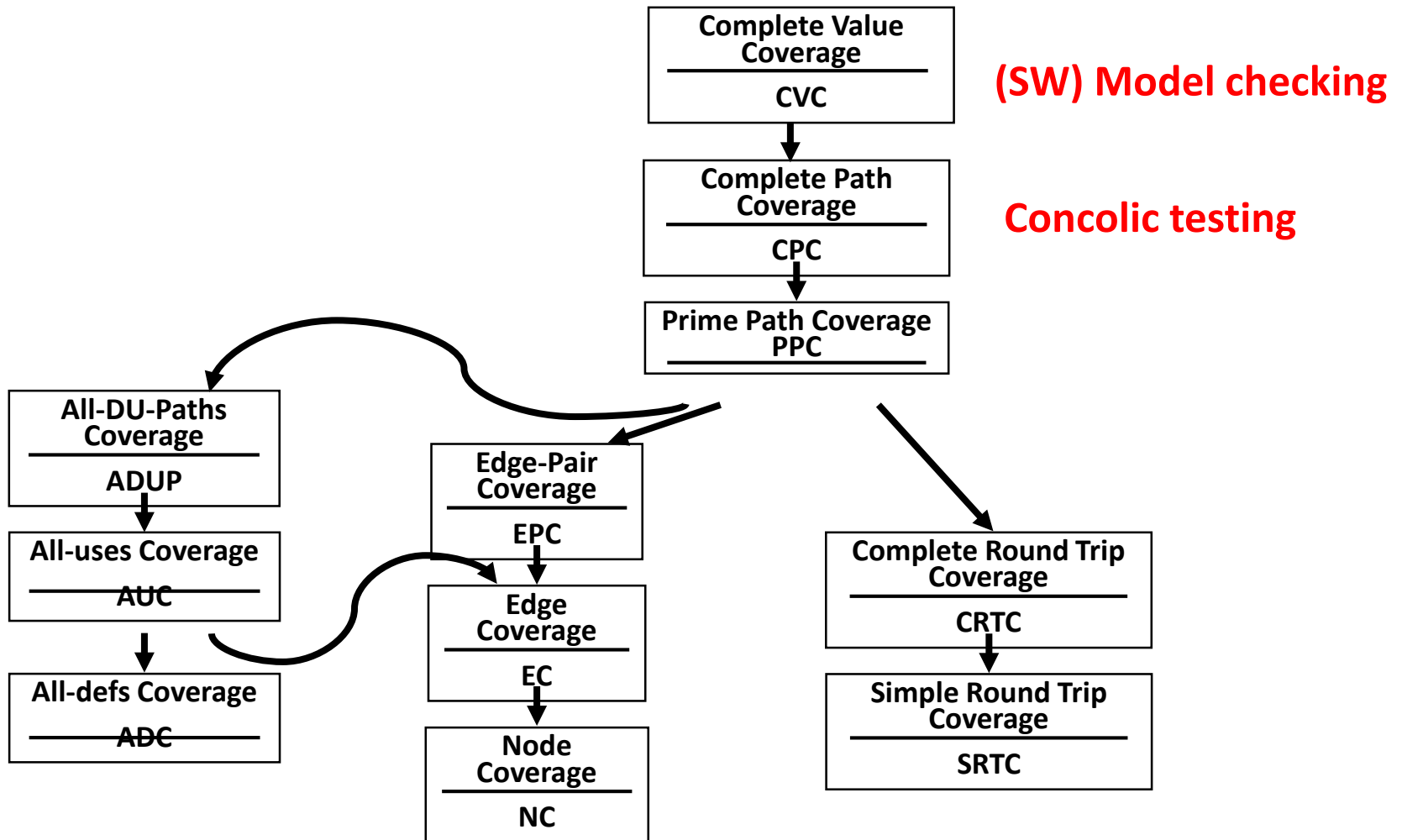


# Graph Coverage Criteria

Moonzoo Kim  
School of Computing  
KAIST

*The original slides are taken from Chap. 7 of Intro. to SW Testing  
2<sup>nd</sup> ed by Ammann and Offutt*

# Hierarchy of Structural/graph Coverages



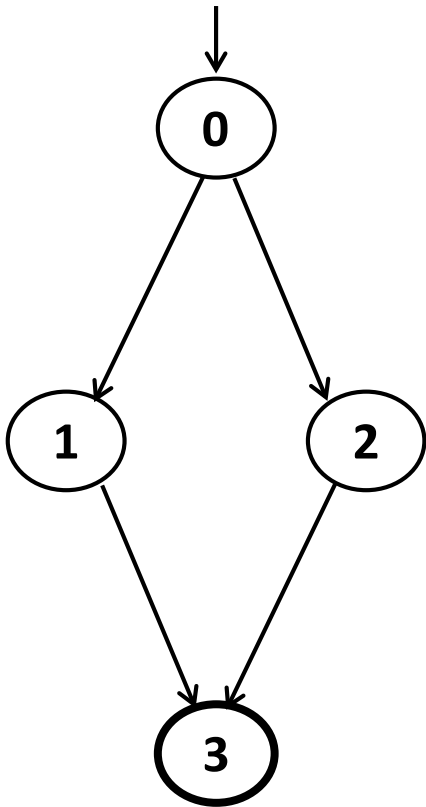
# Covering Graphs

- Graphs are the most **commonly** used structure for testing
- Graphs can come from **many sources**
  - Target source code
  - Control flow graphs
  - Design structure
  - FSMs and statecharts
  - Use cases
- Tests usually are intended to “**cover**” the graph in some way

# Definition of a Graph

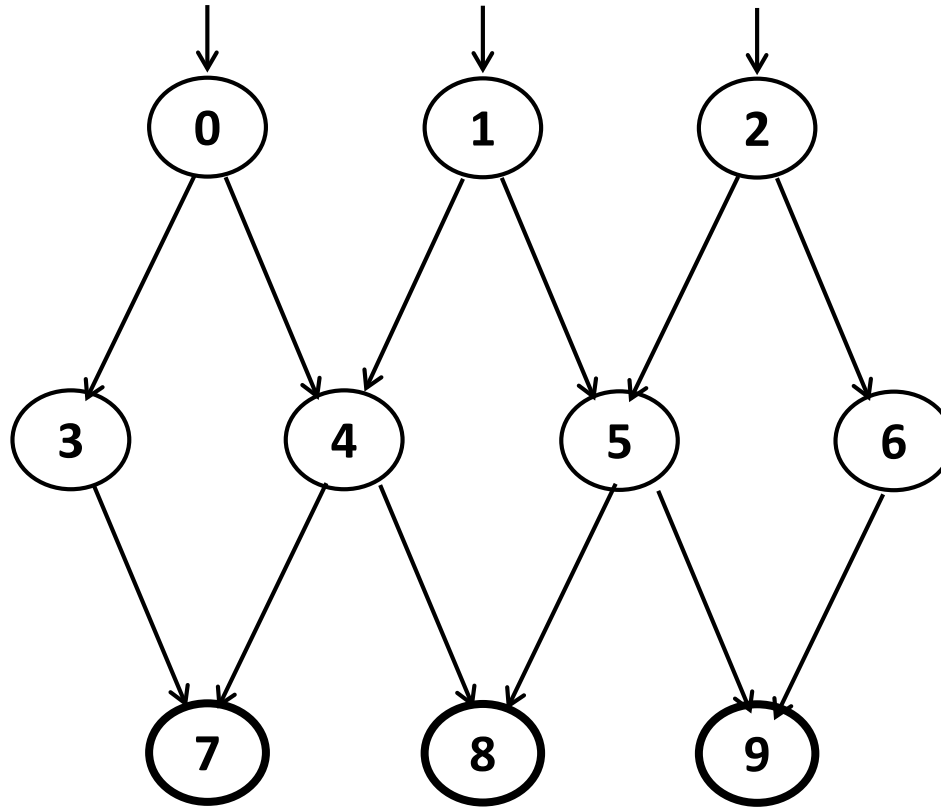
- A set  $N$  of nodes,  $N$  is not empty
- A set  $N_0$  of initial nodes,  $N_0$  is not empty
- A set  $N_f$  of final nodes,  $N_f$  is not empty
- A set  $E$  of edges, each edge from one node to another
  - $(n_i, n_j)$ ,  $n_i$  is predecessor,  $n_j$  is successor

# Three Example Graphs



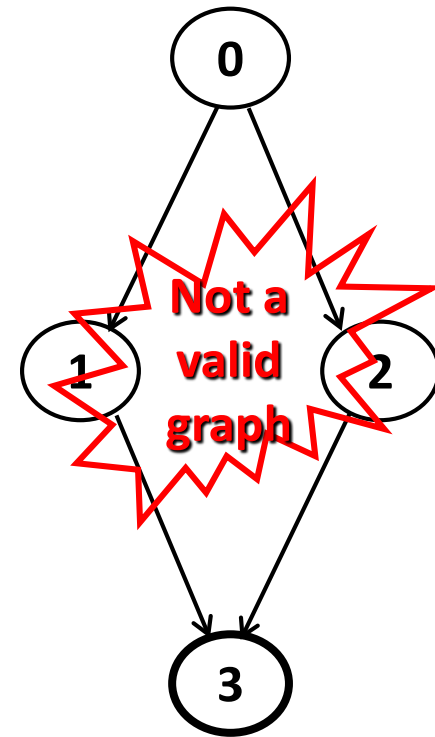
$$N_0 = \{0\}$$

$$N_f = \{3\}$$



$$N_0 = \{0, 1, 2\}$$

$$N_f = \{7, 8, 9\}$$

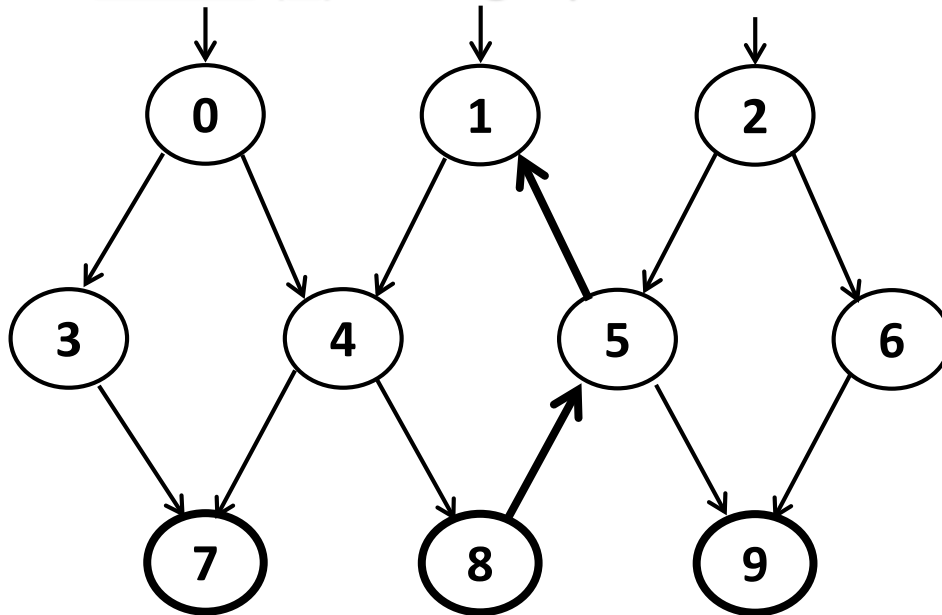


$$N_0 = \{\}$$

$$N_f = \{3\}$$

# Paths in Graphs

- **Path** : A sequence of nodes –  $[n_1, n_2, \dots, n_M]$ 
  - Each pair of nodes is an edge
- **Length** : The number of edges
  - A single node is a path of length 0
- **Subpath** : A subsequence of nodes in  $p$  is a subpath of  $p$
- **Reach** ( $n$ ) : Subgraph that can be reached from  $n$



## Paths

[ 0, 3, 7 ]

[ 1, 4, 8, 5, 1 ]

[ 2, 6, 9 ]

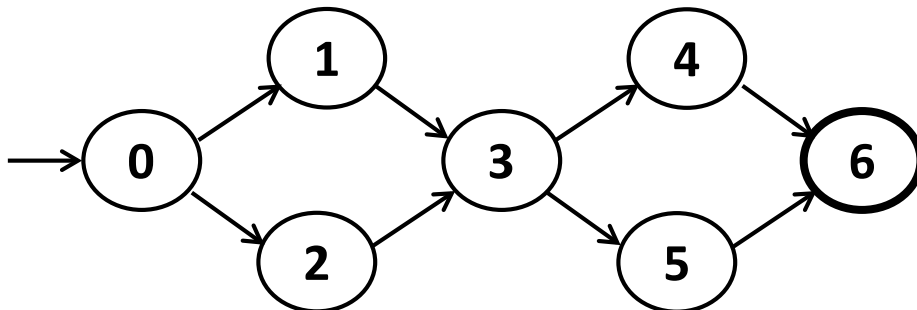
Reach (0) =  $G'$  whose  
set of nodes is

{ 0, 3, 4, 7, 8, 5, 1, 9 }

Reach ({0, 2}) =  $G$

# Test Paths and SESEs

- Test Path : A path that starts at an initial node and ends at a final node
- Test paths represent execution of test cases
  - Some test paths can be executed by many tests
  - Some test paths cannot be executed by any tests
- SESE graphs : All test paths start at a single node and end at another node
  - Single-entry, single-exit
  - N0 and Nf have exactly one node



## Double-diamond graph

### Four test paths

[ 0, 1, 3, 4, 6 ]

[ 0, 1, 3, 5, 6 ]

[ 0, 2, 3, 4, 6 ]

[ 0, 2, 3, 5, 6 ]

# Visiting and Touring

- **Visit** : A test path  $p$  visits node  $n$  if  $n$  is in  $p$   
A test path  $p$  visits edge  $e$  if  $e$  is in  $p$
- **Tour** : A test path  $p$  tours subpath  $q$  if  $q$  is a subpath of  $p$

Path [ 0, 1, 3, 4, 6 ]

Visits nodes 0, 1, 3, 4, 6

Visits edges (0, 1), (1, 3), (3, 4), (4, 6)

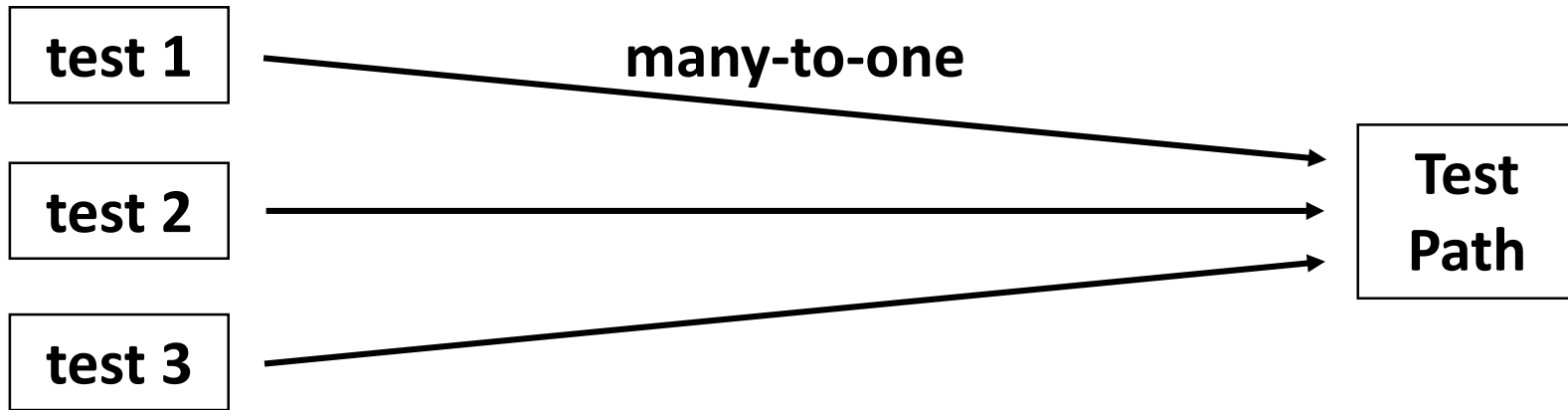
Tours subpaths (0, 1, 3), (1, 3, 4), (3, 4, 6), (0, 1, 3, 4), (1, 3, 4, 6)



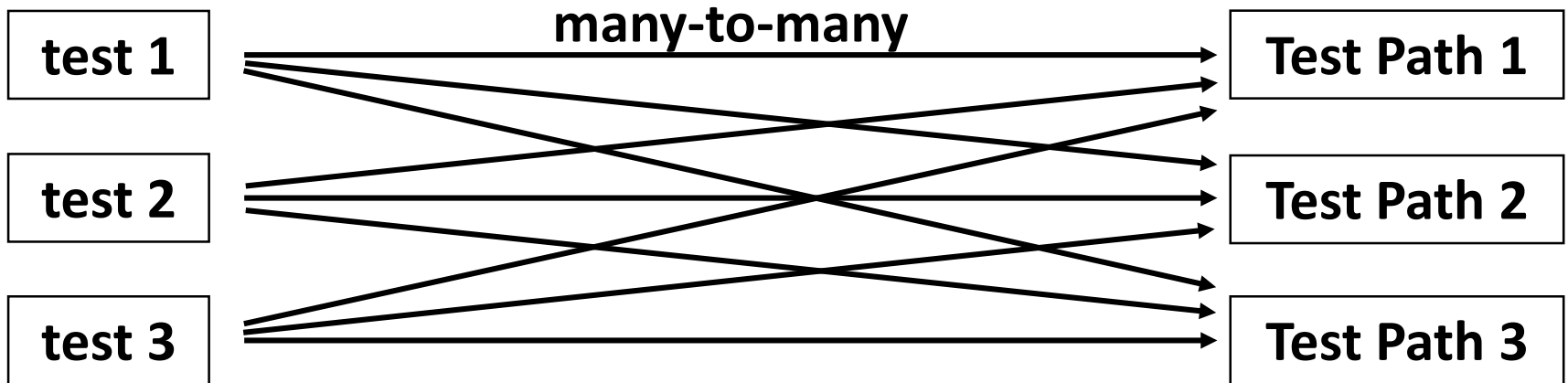
# Tests and Test Paths

- path ( $t$ ) : The test path executed by test  $t$
- path ( $T$ ) : The set of test paths executed by the set of tests  $T$
- Each test executes **one and only one** test path
- A location in a graph (node or edge) can be reached from another location if there is a sequence of edges from the first location to the second
  - Syntactic reach : A subpath exists in the graph
  - Semantic reach : A test exists that can execute that subpath

# Tests and Test Paths



**Deterministic software – a test always executes the same test path**



**Non-deterministic software – a test can execute different test paths**

# Testing and Covering Graphs (2.2)

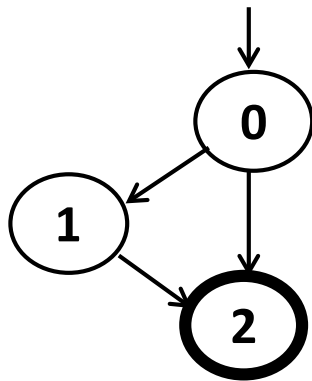
- We use graphs in testing as follows :
  - Developing a model of the software as a graph
  - Requiring tests to visit or tour specific sets of nodes, edges or subpaths
- **Test Requirements (TR)** : Describe properties of test paths
- **Test Criterion** : Rules that define test requirements
- **Satisfaction** : *Given a set TR of test requirements for a criterion C, a set of tests T satisfies C on a graph if and only if for every test requirement in TR, there is a test path in path(T) that meets the test requirement tr*
- **Structural Coverage Criteria** : Defined on a graph just in terms of nodes and edges
- **Data Flow Coverage Criteria** : Requires a graph to be annotated with references to variables

# Node and Edge Coverage

- Edge coverage is slightly stronger than node coverage

**Edge Coverage (EC)** : TR contains each reachable path of length 1 in G.

- NC and EC are only different when there is an edge and another subpath between a pair of nodes (as in an “if-else” statement)



**Node Coverage** : TR = { 0, 1, 2 }

Test Path = [ 0, 1, 2 ]

**Edge Coverage** : TR = { (0,1), (0, 2), (1, 2) }

Test Paths = [ 0, 1, 2 ]

[ 0, 2 ]

# Covering Multiple Edges

- Edge-pair coverage requires **pairs of edges**, or subpaths of length 2

**Edge-Pair Coverage (EPC)** : TR contains each reachable path of length 2, inclusive, in G.

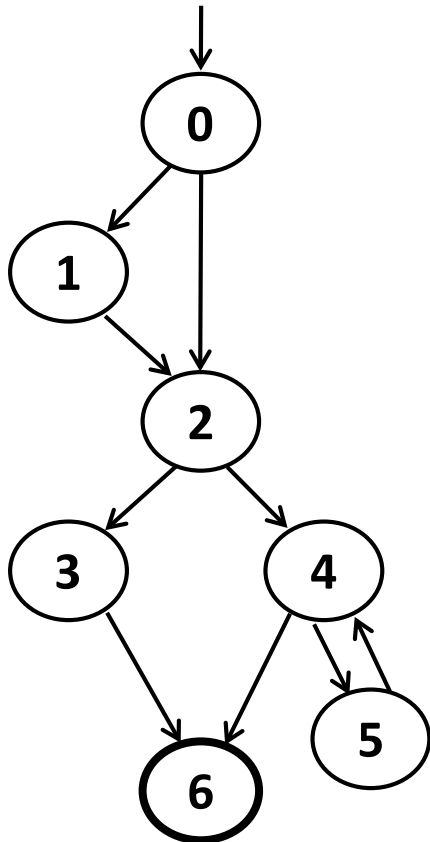
- The logical extension is to require **all paths** ...

**Complete Path Coverage (CPC)** : TR contains all paths in G.

- Unfortunately, this is **impossible** if the graph has a loop, so a weak compromise is to make the tester decide which paths:

**Specified Path Coverage (SPC)** : TR contains a set S of test paths, where S is supplied as a parameter.

# Structural Coverage Example



## Node Coverage

$TR_{NC} = \{ 0, 1, 2, 3, 4, 5, 6 \}$

Test Paths: [ 0, 1, 2, 3, 6 ] [ 0, 1, 2, 4, 5, 4, 6 ]

## Edge Coverage

$TR_{EC} = \{(0,1),(0,2),(1,2), (2,3), (2,4), (3,6), (4,5),(4,6), (5,4)\}$

Test Paths: [ 0, 1, 2, 3, 6 ] [ 0, 2, 4, 5, 4, 6 ]

## Edge-Pair Coverage

$TR_{EPC} = \{ [0,1,2], [0,2,3], [0,2,4], [1,2,3], [1,2,4], [2,3,6], [2,4,5], [2,4,6], [4,5,4], [5,4,5], [5,4,6] \}$

Test Paths: [ 0, 1, 2, 3, 6 ] [ 0, 1, 2, 4, 6 ] [ 0, 2, 3, 6 ]  
[ 0, 2, 4, 5, 4, 5, 4, 6 ]

## Complete Path Coverage

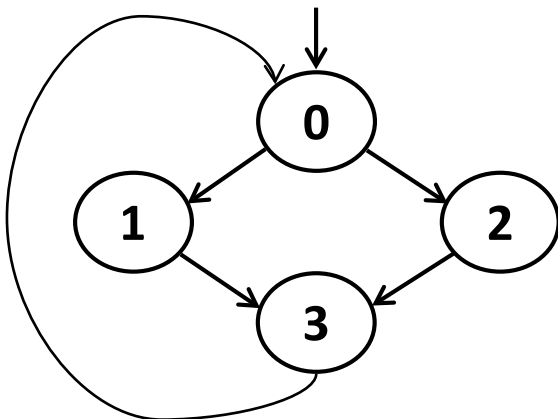
Test Paths: [ 0, 1, 2, 3, 6 ] [ 0, 1, 2, 4, 6 ] [ 0, 1, 2, 4, 5, 4, 6 ] [ 0, 1, 2, 4, 5, 4, 5, 4, 6 ] [ 0, 1, 2, 4, 5, 4, 5, 4, 5, 4, 6 ] ...

# Loops in Graphs

- If a graph contains a loop, it has an infinite number of paths
  - Thus, CPC is not feasible to satisfy
- Attempts to “deal with” loops:
  - **1980s** : Execute each loop, exactly once ([4, 5, 4] in previous example)
  - **1990s** : Execute loops 0 times, once, more than once
  - **2000s** : Prime paths

# Simple Paths and Prime Paths

- **Simple Path** : A path from node  $n_i$  to  $n_j$  is simple, if no node appears more than once, except possibly the first and last nodes are the same
  - No internal loops
  - Includes all other subpaths
  - A loop is a simple path
- **Prime Path** : A simple path that does **not** appear as a proper subpath of any other simple path



**Simple Paths** : [ 0, 1, 3, 0 ], [ 0, 2, 3, 0 ], [ 1, 3, 0, 1 ],  
[ 2, 3, 0, 2 ], [ 3, 0, 1, 3 ], [ 3, 0, 2, 3 ], [ 1, 3, 0, 2 ],  
[ 2, 3, 0, 1 ], [ 0, 1, 3 ], [ 0, 2, 3 ], [ 1, 3, 0 ], [ 2, 3, 0 ],  
[ 3, 0, 1 ], [ 3, 0, 2 ], [ 0, 1 ], [ 0, 2 ], [ 1, 3 ], [ 2, 3 ], [ 3, 0 ],  
[ 0 ], [ 1 ], [ 2 ], [ 3 ]

**Prime Paths** : [ 0, 1, 3, 0 ], [ 0, 2, 3, 0 ], [ 1, 3, 0, 1 ],  
[ 2, 3, 0, 2 ], [ 3, 0, 1, 3 ], [ 3, 0, 2, 3 ], [ 1, 3, 0, 2 ],  
[ 2, 3, 0, 1 ]



# Prime Path Coverage

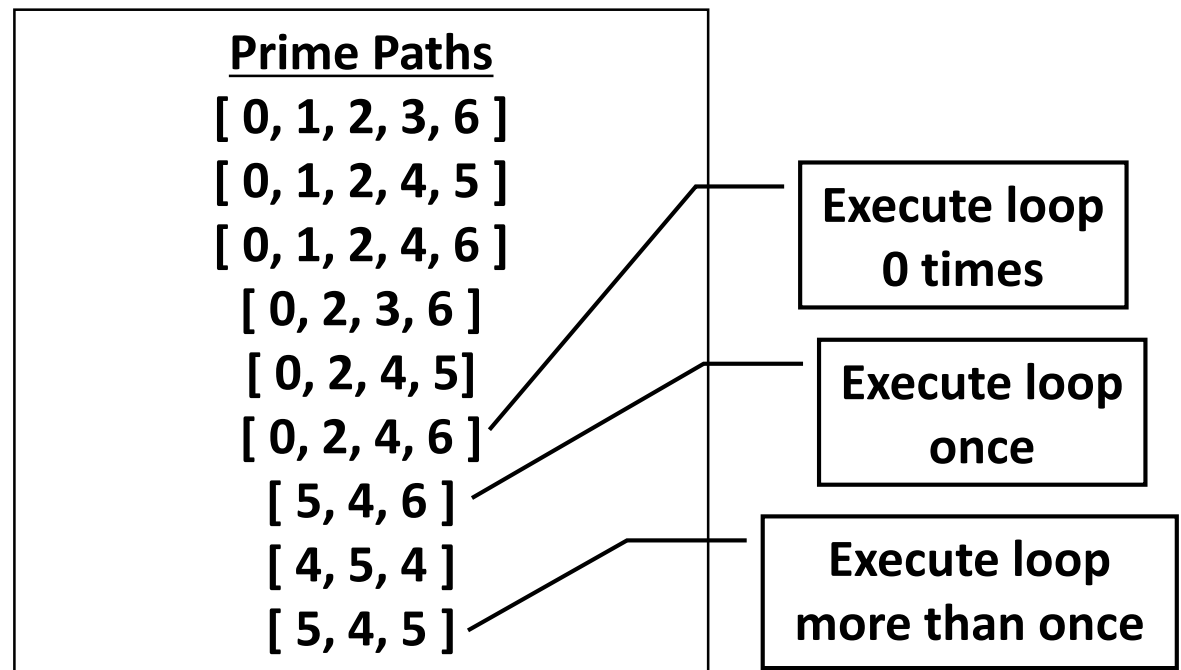
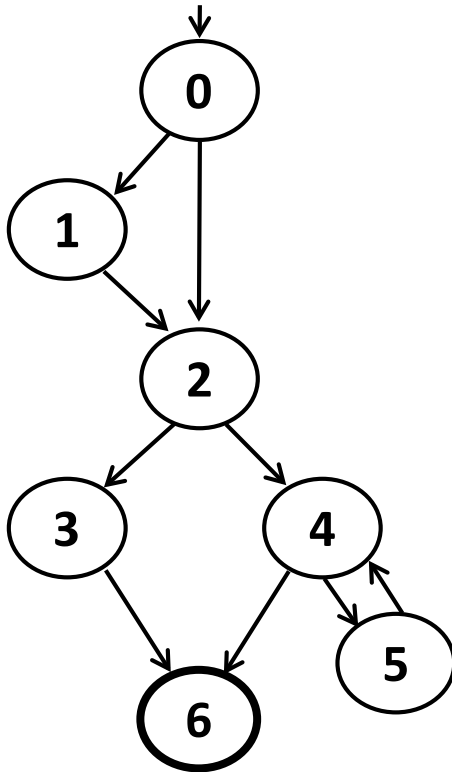
- A simple, elegant and finite criterion that requires **loops** to be executed as well as skipped

**Prime Path Coverage (PPC)** : TR contains each prime path in G.

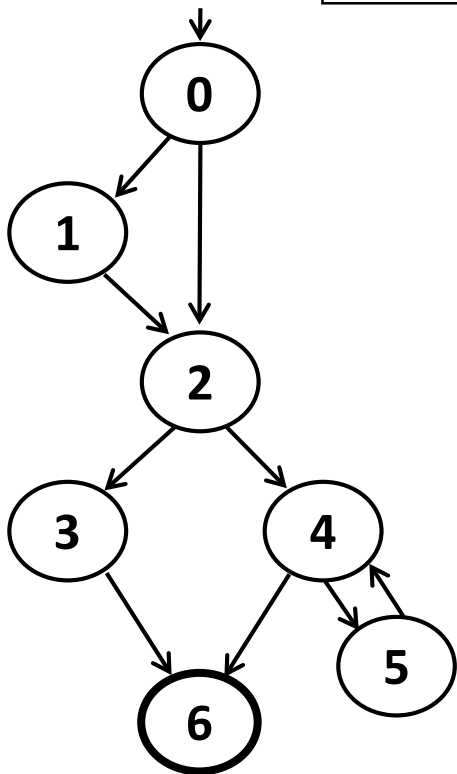
- Will tour all paths of length 0, 1, ...
- That is, it **subsumes** node, edge, and edge-pair coverage

# Prime Path Example

- The previous example has 38 **simple** paths
- Only **nine prime paths**



# Simple & Prime Path Example



Simple paths

- Len 0
- [0]
  - [1]
  - [2]
  - [3]
  - [4]
  - [5]
  - [6] !

- Len 1
- [0, 1]
  - [0, 2]
  - [1, 2]
  - [2, 3]
  - [2, 4]
  - [3, 6] !
  - [4, 6] !
  - [4, 5]
  - [5, 4]

- Len 2
- [0, 1, 2]
  - [0, 2, 3]
  - [0, 2, 4]
  - [1, 2, 3]
  - [1, 2, 4]
  - [2, 3, 6] !
  - [2, 4, 6] !
  - [2, 4, 5] !
  - [4, 5, 4] \*
  - [5, 4, 6] !
  - [5, 4, 5] \*

- Len 3
- [0, 1, 2, 3]
  - [0, 1, 2, 4]
  - [0, 2, 3, 6] !
  - [0, 2, 4, 6] !
  - [0, 2, 4, 5] !
  - [1, 2, 3, 6] !
  - [1, 2, 4, 5] !
  - [1, 2, 4, 6] !

is path es

- Len 4
- [0, 1, 2, 3, 6] !
  - [0, 1, 2, 4, 6] !
  - [0, 1, 2, 4, 5] !

**Prime Paths**

Note that paths w/o ! or \* cannot be prime paths

# Round Trips

- Round-Trip Path : *A prime path that starts and ends at the same node*

**Simple Round Trip Coverage (SRTC)** : TR contains at least one round-trip path for each reachable node in G that begins and ends a round-trip path.

**Complete Round Trip Coverage (CRTC)** : TR contains all round-trip paths for each reachable node in G.

- These criteria **omit nodes and edges** that are not in round trips
- That is, they do **not** subsume edge-pair, edge, or node coverage

# Infeasible Test Requirements

- An **infeasible** test requirement cannot be satisfied
  - Unreachable statement (dead code)
  - A subpath that can only be executed if a contradiction occurs ( $X > 0$  and  $X < 0$ )
- Most test **criteria** have some infeasible test requirements
- It is usually **undecidable** whether all test requirements are feasible
- When sidetrips are not allowed, many structural criteria have **more infeasible test requirements**
- However, always allowing **sidetrips weakens** the test criteria

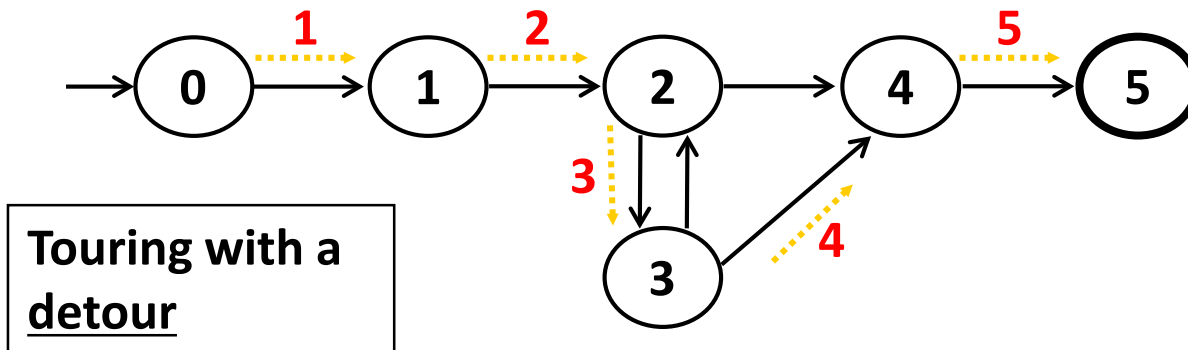
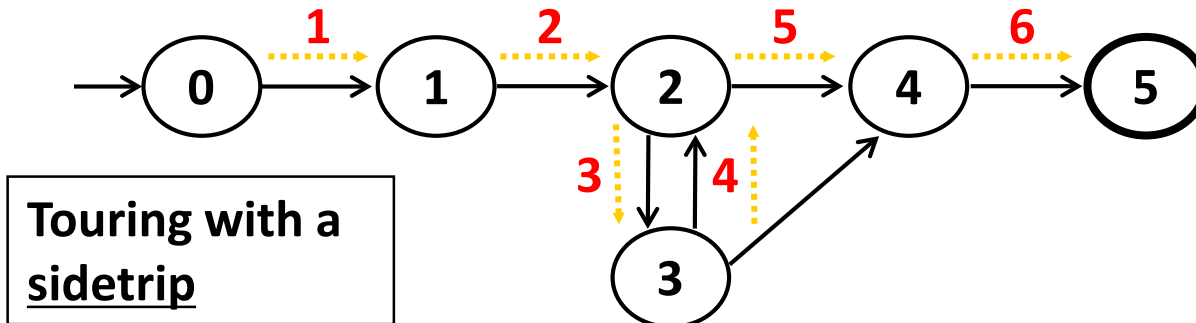
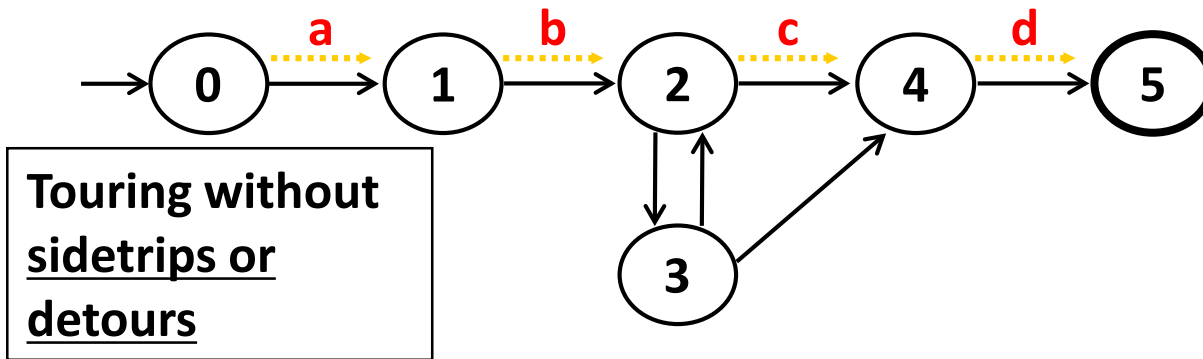
## Practical recommendation – Best Effort Touring

- Satisfy as many test requirements as possible without sidetrips
- Allow sidetrips to try to satisfy unsatisfied test requirements

# Touring, Sidetrips and Detours

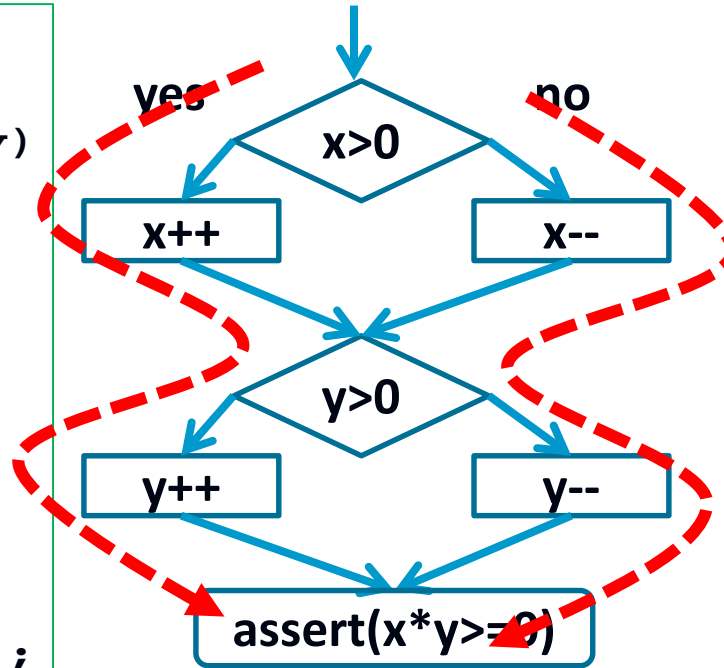
- Prime paths do not have **internal loops** ... test paths might
- **Tour** : A test path  $p$  tours subpath  $q$  if  $q$  is a subpath of  $p$
- **Tour With Sidetrips** : A test path  $p$  tours subpath  $q$  with sidetrips iff every edge in  $q$  is also in  $p$  in the same order
  - The tour can include a sidetrip, as long as it comes back to the same node
- **Tour With Detours** : A test path  $p$  tours subpath  $q$  with detours iff every node in  $q$  is also in  $p$  in the same order

# Sidetrrips and Detours Example



# Weaknesses of the Purely Structural Coverage

```
/* TC1: x= 1, y= 1;
   TC2: x=-1, y=-1;*/
void foo(int x, int y)
{
    if ( x > 0 )
        x++;
    else
        x--;
    if(y >0)
        y++;
    else
        y--;
    assert (x * y >= 0);
}
```



Purely structural coverage (e.g., branch coverage) alone **cannot** improve the quality of target software sufficiently  
-> **Advanced semantic testing** should be accompanied



# Final Remarks

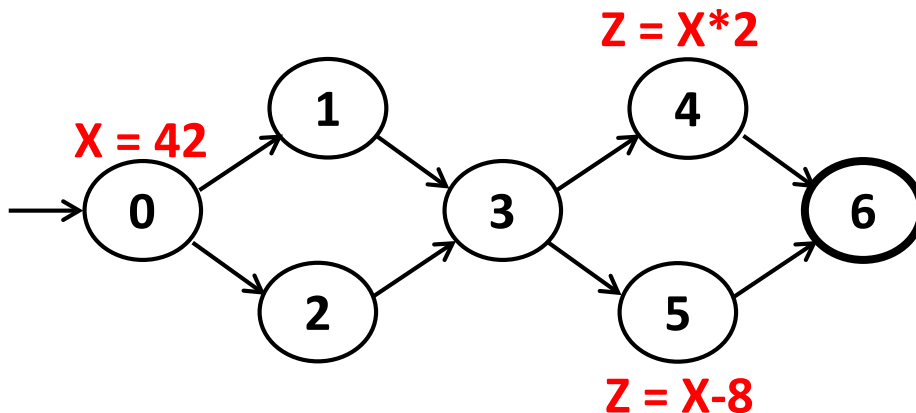
1. Why are coverage criteria important for testing?
2. Why is branch coverage popular in industry?
3. Why is prime path coverage not used in practice?
4. Why is it difficult to reach 100% branch coverage of real-world programs?

# Data Flow Coverage

# Data Flow Criteria

Goal: Try to ensure that **values** are computed and used **correctly**

- Definition : A location where a value for a variable is stored into memory
- Use : A location where a variable's value is accessed
- def (n) or def (e) : The set of variables that are defined by node n or edge e
- use (n) or use (e) : The set of variables that are used by node n or edge e



Defs:  $\text{def}(0) = \{X\}$   
 $\text{def}(4) = \{Z\}$   
 $\text{def}(5) = \{Z\}$   
Uses:  $\text{use}(4) = \{X\}$   
 $\text{use}(5) = \{X\}$

# DU Pairs and DU Paths

- DU pair : A pair of locations  $(l_i, l_j)$  such that a variable  $v$  is defined at  $l_i$  and used at  $l_j$
- Def-clear : A path from  $l_i$  to  $l_j$  is *def-clear* with respect to variable  $v$ , if  $v$  is not given another value on any of the nodes or edges in the path
  - Reach : If there is a def-clear path from  $l_i$  to  $l_j$  with respect to  $v$ , the def of  $v$  at  $l_i$  reaches the use at  $l_j$
- du-path : A simple subpath that is def-clear with respect to  $v$  from a def of  $v$  to a use of  $v$
- du  $(n_i, n_j, v)$  – the set of du-paths from  $n_i$  to  $n_j$
- du  $(n_i, v)$  – the set of du-paths that start at  $n_i$

# Touring DU-Paths

- A test path  $p$  *du-tours* subpath  $d$  with respect to  $v$  if  $p$  tours  $d$  and the subpath taken is def-clear with respect to  $v$
- **Sidetrips** can be used, just as with previous touring
- Three criteria
  - Use every def
  - Get to every use
  - Follow all du-paths

# Data Flow Test Criteria

- First, we make sure **every def** reaches **a use**

All-defs coverage (ADC) : For each set of du-paths

$S = du(n, v)$ , TR contains at least one path  $d$  in  $S$ .

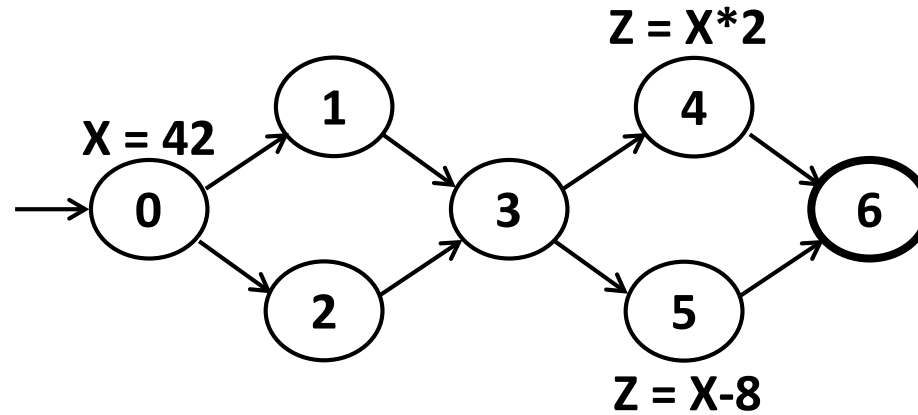
- Then we make sure that **every def** reaches **all possible uses**

All-uses coverage (AUC) : For each set of du-paths to uses  $S = du(n_i, n_j, v)$ , TR contains at least one path  $d$  in  $S$ .

- Finally, we cover **all the paths** between defs and uses

All-du-paths coverage (ADUPC) : For each set  $S = du(n_i, n_j, v)$ , TR contains every path  $d$  in  $S$ .

# Data Flow Testing Example



All-defs for $X$
[ 0, 1, 3, 4 ]

All-uses for $X$
[ 0, 1, 3, 4 ]
[ 0, 1, 3, 5 ]

All-du-paths for $X$
[ 0, 1, 3, 4 ]
[ 0, 2, 3, 4 ]
[ 0, 1, 3, 5 ]
[ 0, 2, 3, 5 ]

# Graph Coverage Criteria Subsumption

## Assumptions for Data Flow Coverage

1. Every use is preceded by a def
2. Every def reaches at least one use
3. For every node with multiple outgoing edges, at least one variable is used on each out edge, and the same variables are used on each out edge.

