# Temporal Logic - LTL, CTL, and CTL\*

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# **CTL is not more expressive than LTL**

# CTL cannot select a range of paths FG p in LTL is not equivalent to AF AG p M,s₀ ⊨ FG p but M,s₀ ⊭ AF AG p AF AG p is strictly stronger than FG p AF EG p is strictly weaker than FG p Similarly, F p → F q is not equivalent to AF p → AF q, neither to AG (p → AF q) Remark FX p ≡ X F p in LTL

AF AX p is not equivalent to AX AF p





# CTL\*

- CTL\* combines the expressive powers of LTL and CTL
- Syntax of CTL\*
  - State formula  $\phi ::= T | p | \neg \phi | \phi \land \phi | A [\alpha] | E[\alpha]$
  - Path formula  $\alpha ::= \phi \mid \neg \alpha \mid \alpha \land \alpha \mid \alpha \cup \alpha \mid \mathsf{G} \mid \alpha \mid \mathsf{F} \mid \alpha \mid \mathsf{X} \mid \alpha$
- LTL is a subset of CTL\*
  - LTL formula  $\alpha$  is equivalent to A[ $\alpha$ ] in CTL\*
- CTL is a subset of CTL\*
  - We restrict  $\alpha ::= \phi \cup \phi \mid \mathsf{G} \phi \mid \mathsf{F} \phi \mid \mathsf{X} \phi$ 
    - No boolean connectives in path formula
      - Not real limitation. See page 6
    - No nesting of the path modalities X,F, and G



### **Relationship between LTL, CTL, and CTL\***





## **Relationship between LTL,CTL, and CTL\***



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### **Boolean combinations of temporal formulas in CTL**

We can translate any CTL formula having boolean combinations of path formulas into a CTL formula that does not.

Examples

- $E[Fp \land Fq] \equiv EF[p \land EFq] \lor EF[q \land EFp]$ 
  - If we have F  $p \land F q$  along any path, then either the p must come before the q, or the other way around
- E [  $(p_1 \cup q_1) \land (p_2 \cup q_2)$ ] = E[ $(p_1 \land p_2) \cup (q_1 \land E[p_2 \cup q_2])$ ]  $\lor E[(p_1 \land p_2) \cup (q_2 \land E[p_1 \cup q_1])]$
- $E[\neg(p \cup q)] \equiv E[\neg q \cup (\neg p \land \neg q)] \lor EG \neg q$ 
  - since A [p U q] =  $\neg$ (E[ $\neg$ q U ( $\neg$ p  $\land \neg$ q)]  $\lor$  EG  $\neg$ q)
- $E[\neg X p] \equiv EX \neg p$



# **Complexity of Model Checking**

- Let  $\mathcal{M}$  be a target transition system with N states and M transitions
- Upper bound of model checking complexity
  - LTL-formula  $\phi$  :  $O((N+M) \cdot 2^{|\phi|})$
  - CTL-formula  $\phi$  :  $O((N+M) \cdot |\phi|)$
  - CTL\*-formula  $\phi$  :  $O((N+M)\cdot 2^{|\phi|})$
- Lower bound of model checking complexity
  - **LTL-formula**  $\phi$  : **PSpace-hard -> PSpace-complete** 
    - Note that  $P \subseteq NP \subseteq PSpace \subseteq EXP \subseteq EXPSpace$
  - CTL-formula  $\phi$  : P-hard -> P-complete
  - CTL\*-formula \(\phi\) : PSpace-hard -> PSpace-complete
- For more details, "The Complexity of Temporal Logic Model Checking" by Ph. Schnoebelen

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