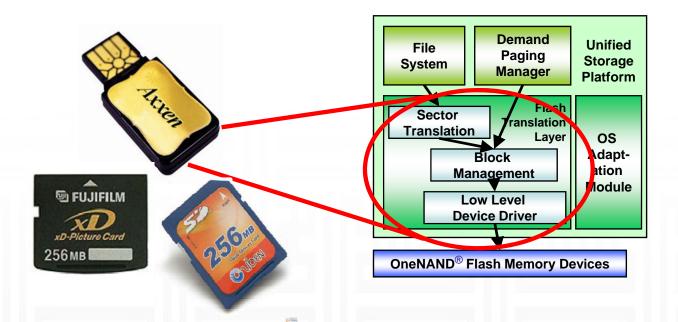
Formal Verification of a Flash Memory Device Driver - an Experience Report

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Summary of the Talk



 In 2007, Samsung requested to debug the device driver for the Samsung OneNAND[™] flash memory, by using model checkers, for 6 months. This presentation describes a part of the result from the project.

2

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Overview

3

- Background
 - Overview of the Unified Storage Platform (USP)
 - Sector Translation Layer (STL)
 - Multi-Sector Read operation (MSR)
- Model Checking MSR
 - Reports on the following three aspects
 - Target system modeling
 - Environment modeling
 - Performance analysis on the verification
- Three different types of model checkers are used
 - BDD based symbolic model checking (NuSMV)
 - Explicit model checking (Spin)
 - C-bounded model checking (CBMC)

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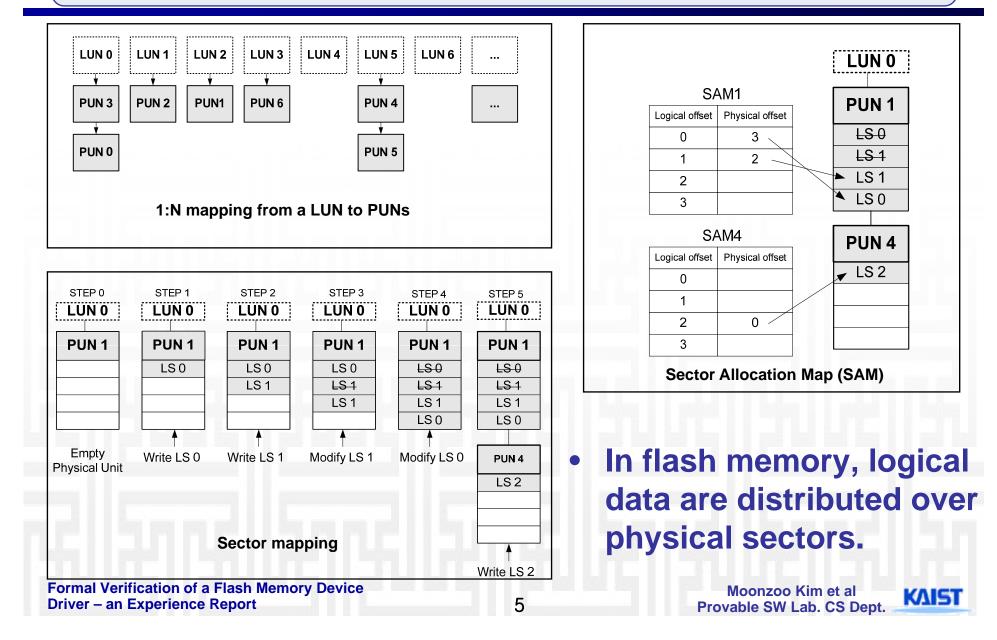


PART I: Background

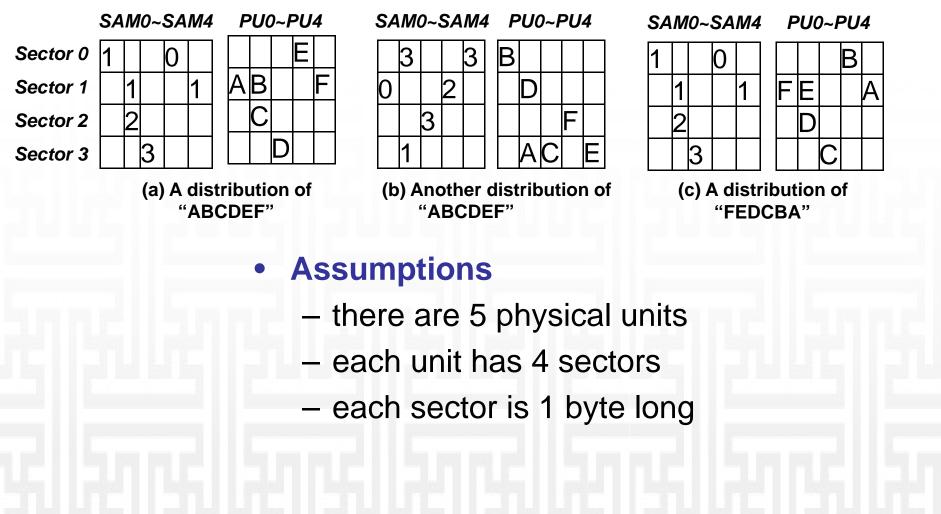
- Logical-to-physical sector translation
 - Example of possible data distributions
- Unified Storage Platform (USP)
 - Block diagram
 - Code statistics
- Multi-Sector Read operation (MSR)
 - Pseudo structure



Logical to Physical Sector Mapping



Examples of Possible Data Distribution



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6

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Environment Model

Environment model creation

- The environment of MSR (i.e., PUs and SAMs configurations) can be described by invariant rules. Some of them are
 - 1. One PU is mapped to at most one LU
 - 2. Valid correspondence between SAMs and PUs:

If the *i* th LS is written in the *k* th sector of the *j* th PU, then the *i* th offset of the *j* th SAM is valid and indicates the k'th PS,

Ex> 3^{rd} LS ('C') is in the 3^{rd} sector of the 2^{nd} PU, then SAM1[2] ==2

i=2

i=3 k=3

3. For one LS, there exists only one PS that contains the value of the LS: The PS number of the *i* th LS must be written in only one of the (*i* mod 4) th offsets of the SAM tables for the PUs mapped to the corresponding LU.

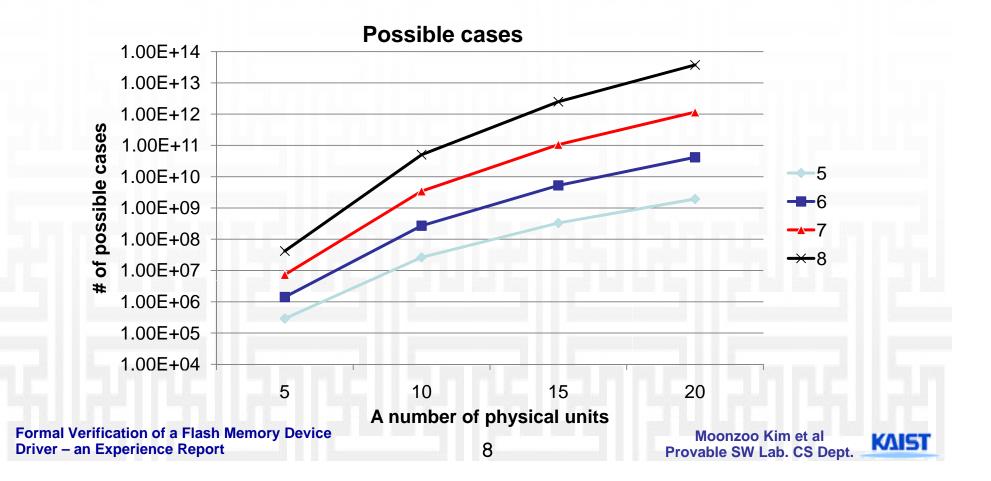
$$\begin{array}{l} \forall i,j,k \ (LS[i]=PU[j].sect[k] \rightarrow (SAM[j].valid[i \ mod \ m]=true \\ \& \ SAM[j].off set[i \ mod \ m]=k \\ \& \ \forall p.(SAM[p].valid[i \ mod \ m]=false) \\ & \text{where} \ p \neq j \ \text{and} \ PU[p] \ \text{is mapped to}\lfloor \frac{i}{m} \rfloor_{th} \ LU)) \end{array} \begin{array}{l} \textbf{S} \\ \textbf$$

SAM0~SAM4 Sector 0 Sector 1 B Sector 2 Sector 3

PU0~PU4

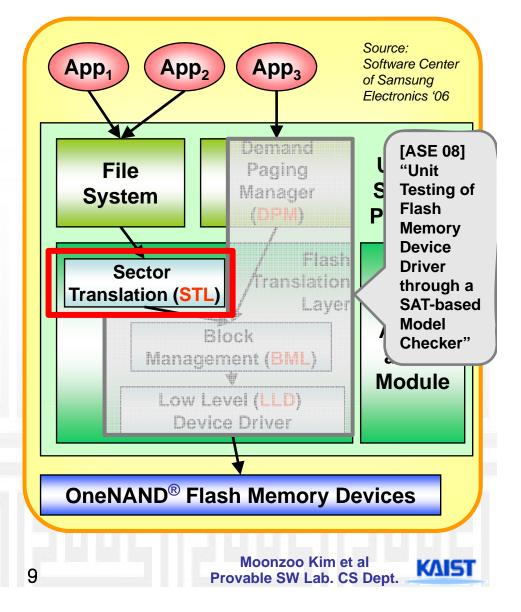
Exponential Increase of Distribution Cases

$$\sum_{i=1}^{n-1} ({}_{(4\times i)}C_4 \times 4!) \times ({}_{(4\times (n-i))}C_{(l-4)} \times (l-4)!)$$



Overview of the OneNAND® Flash Memory

- Characteristics of OneNAND®
 - Each memory cell can be written limited number of times only
 - Logical-to-physical sector mapping
 - Bad block management
 - Wear-leveling
 - Performance enhancement
 - Multi-sector read/write
 - Asynchronous operations
 - Deferred operation result check



PART II: Model Checking Results

- Verification of MSR by using NuSMV, Spin, and CBMC
 - NuSMV: BDD-based symbolic model checker
 - Spin: Explicit model checker
 - CBMC: C-bounded model checker
- The requirement property is to check
 - after_MSR -> (∀i. logical_sectors[i] == buf[i])
- We compared these three model checkers empirically



Excerpts of the SMV Model

MODULE main

```
-- Variable declaration
```

VAR

SAM : array 0..4 of sam_type; PU : array 0..4 of PU_type; buf : array 0..4 of 0..5; nScts : 0..5;

```
-- SPEC
INVARSPEC (after_first_do ->
PU[0].sect[0]=1 &
PU[0].sect[1]=2 &
PU[0].sect[2]=3 &
PU[0].sect[2]=3 &
PU[0].sect[3]=4 &
PU[3].sect[0]=5)
```

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init(buf[0]):=0;

- -- if(pBuf==0 && 0 < nScts)
- -- buf[0]= PU[PU_id].sect[nFirstOffset]
 next(buf[0]):

case after_fourth_do :

```
case pBuf = 0 & 0 < nScts: -- i=0
```

case

PU_id=0 & nFirstOffset=0: PU[0].sect[0]; PU_id=0 & nFirstOffset=1: PU[0].sect[1]; PU_id=0 & nFirstOffset=2: PU[0].sect[2]; PU_id=0 & nFirstOffset=3: PU[0].sect[3];

PU_id=4 & nFirstOffset=3 : PU[4].sect[3]; esac; esac;

init(buf[1]):=0; next(buf[1]):= ...

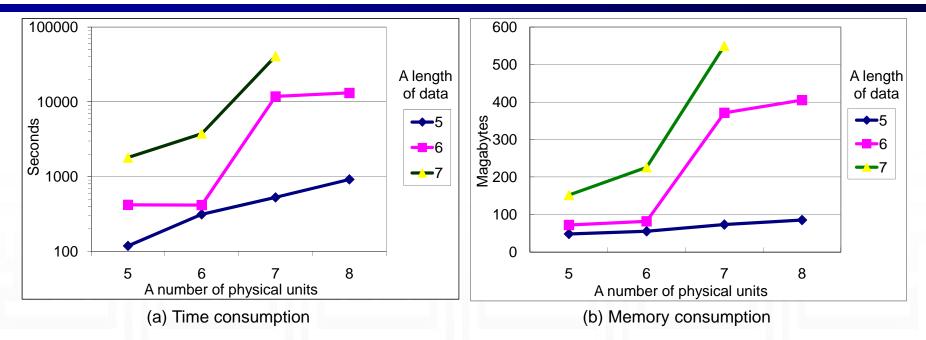
11

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Verification Performance of NuSMV



- Verification was performed on the machine equipped with Xeon5160 (3Ghz, 32Gbyte Memory), 64 bit Fedora Linux 7, NuSMV 2.4.3
- The requirement property was proved correct for all the experiments (i.e., MSR is correct in this small model)
 - For 7 sectors long data that are distributed over 7 PUs consumes more than 11 hours while consuming only 550 mb memory

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12

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Excerpts of the Spin Model

```
active proctype SM ReadSectors() {
```

```
byte buf[NUM_LS_USED];
byte nScts;
byte nFirstOffset;
byte nNumOfScts=NUM LS USED;
byte nReadScts=nNumOfScts;
byte nSamIdx;
```

```
do /* 1047: while (nNumOfScts >0) { */
```

```
:: nNumOfScts > 0 ->
```

```
PU id = lui[nLun]:
```

```
/* nReadScts = ... */
if
```

```
:: (SECT_PER_U-nSamIdx)> nNumOfScts ->
 nReadScts = nNumOfScts;
```

```
:: else->nReadScts =SECT PER U- nSamIdx;
fi:
```

```
nNumOfScts = nNumOfScts - nReadScts;
```

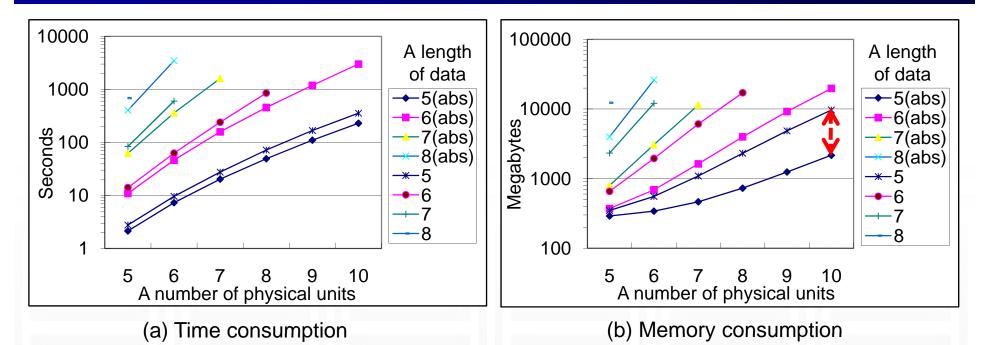
```
/* line 1068: while (nReadScts > 0) */
do
:: (nReadScts > 0) -> PU_id = lui[nLun];
  nFirstOffset=255;
  nScts=1; nReadScts--;
```

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```
do /* line 1075: do {... */
 :: true:
   if /* line 1077: if(pstCurrent->pSam[nSamIdx]...*/
   :: SAM[PU id].valid[nSamIdx]-> nFirstOffset =
     SAM[PU_id].offset[nSamIdx];nSamIdx++;
     do /* line 1084:while (nReadScts > 0) { ... } */
     :: (nReadScts > 0) ->
       if
       ::FirstOffset+nScts==
         SAM[PU id].offset[nSamIdx] ->
         nScts++:nReadScts--:nSamIdx++:
       :: else-> break;
       fi:
     :: else->break:
     od:
     BML MRead(PU id.nFirstOffset.nScts.pBuf);
     break:
   :: else;
   fi;
   if /*line 1112: } while ( PU[PU_id].nil != true) */
   :: PU[PU_id].nil -> break;
   :: else:
   fi:
   PU id++;
 od;
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13
```

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Verification Performance of Spin



The requirement property was satisfied

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The data abstraction technique shows significant performance improvement upto 78% of memory reduction and 35% time reduction (for 5 logical sectors data)

	# of physical units	5	6	7	8	9	10	488
	Memory reduction	17%	38%	57%	68%	74%	78%	
N	Time reduction	23%	24%	26%	32%	34%	35%	1200 Kim et al

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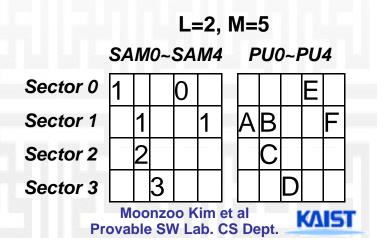
Modeling by CBMC

- CBMC does not require an explicit target model creation
- An environment for MSR was specified using assume statements and the environment model was similar to the environment model in NuSMV
- For the loop bounds, we can get valid upper bounds from the loop structure and the environment setting
 - The outermost loop: L times (L is a # of LUs)
 - The 2nd outermost loop: 4 times (one LU contains 4 LS's)

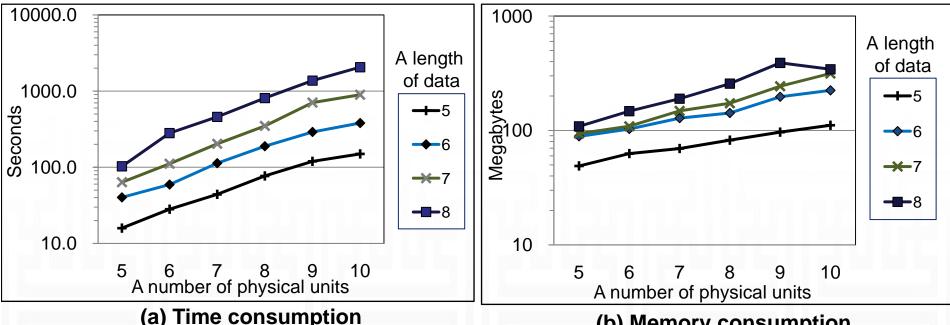
15

- The 3rd outermost loop: M times
 - (M is a # of PUs)
- The innermost loop: 4 times (one PU contains 4 PS's)

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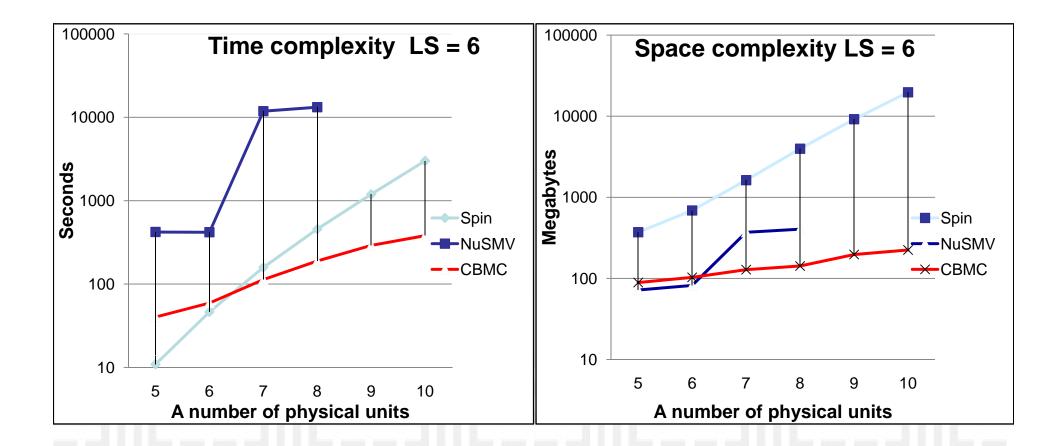


Verification Performance of CBMC



- (b) Memory consumption
- Exponential increase in both time and memory. However, the slope is much lower than those of NuSMV and Spin, which makes **CBMC** perform better for large problems
- A problem of 10 PUs and 8 LS's has 8.6x10⁵ variables and 2.9 x 10⁶ clauses.

Performance Comparison



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17

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Conclusion

- **Application of Model Checking to Industrial SW Project**
 - Current off-the-shelf model checkers showed their effectiveness to debug a part of industrial software, if a target portion is carefully selected
 - Although model checker worked on a small scale problem, it still contributes due to its exhaustive exploration which is complementary to the testing result
- **Comparison among the Three Model Checkers**

	Modeling Difficulty	Memory Usage	Verification Speed
NuSMV	Most difficult	Good	Slow
Spin	Medium difficult	Poor	Fast
CBMC	Easiest	Best	Fastest